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For xp p= e−t,x ′ = −e−t,x ′ = e−t. So x ′ − 3x ′ +2xp= e−t+3e−t+2e−t= 6e−t=r.h.s. The general solution is thus x = c1et+ c2e2t+ e−t. (b) Using the initial conditions x(0) = 4, x′(0) = 3 for the first solution we get, 4 = c1+ c2+2 and 3 = c1+2c2. Solving these equations for for c1and c2we have c1= c2= 1.

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x3=2sinx x1=2cosxC 3 4 x1=2sinxCx1=2cosx 1 2 x1=2sinxCx3=2sinx 1 4 x1=2sinx Cc2. x3=2cosxCx1=2sinxC 3 4 x1=2cosx x1=2sinx 1 2 x1=2cosxCx3=2cosx 1 4 x1=2cosx C4xC x2. 1 4 .4xC8/D 4x3C8x2C 3x 2. 1.2.4. (a) If y0D xex, thenyD xexC R exdxCcD .1 x/exCc, and y.0/D 1) 1D 1Cc, so cD 0and yD .1 x/ex.

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reads r(0) = h, r_(0) = 0. The equation of motion reads r = M (R+ r)2 (exact model) respectively r = g (approximate model); where g= M=R2 and R, Mare the radius, mass of the earth, respectively. (i) Transform both equations into a rst-order system. (ii) Compute the solution to the approximate system corresponding to the given initial condition.

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